

SPECIFICATIONS

1. INPUT		3. OUTPUT	
*Thermocouple	J, K, T, E, B, R, S, N (IPTS68/DIN 43710)	*Relay	5A/240VAC resistive.
*RTD	Pt100 ohms RTD (DIN 43760/BS 1904 or JIS)	*Pulsed Voltage	Isolated 24 VDC 100mA Max.
*Linear Voltage (current)	4-20mA, 0-5VDC, 0-10VDC...	*Current	Isolated 0 (4) - 20 mA Max load 500 ohms.
*Range	User configurable	*Alarm	Relay output, (SPST) 10A/240VAC resistive.
*Accuracy	+/-2C for T/C, +0.2C for RTD, +0.05% for Linear	4. POWER	85 - 265 VAC 50/60Hz 5VA max or 24VDC
*Cold Junction Compensation	0.1% ambient typical.	*Rating	
*Input Impedance	10M ohms for T/C, 100K ohms for Lin. Voltage, 2.7 Ohms for 0 (4)- 20 mA/	5. ENVIRONMENTAL	
*Excitation Current for RTD	0.2mA Max.	*Operating Temp	-10 - 50C
*Sample Rate	250mS	*Humidity	- 90%
2. CONTROL		*Insulation	20M ohms minimum @ 500VDC
*Proportional Band	0.0-300.0%	*EMC Emission	EN50081-1:1992, EN55022:1994
*Rest (Integral)	0-3600 Sec.	*EMC Immunity	EN 50082-1:1992, IEC 801-3, IEC 801-4:1988
*Rate (Derivative)	0-900 Sec.	*Weight	MT4850 180g, MT4950 240g, MT9650 240g
*Anti Rest Windup	Inhibit integral action outside Proportion Band		
*Ramp Rate	0.0-100.0C / minute.		
**On-Off	With adjustable hysteresis		
*Cycle Time	0-99 seconds.		
*Control Action	Configurable for Direct (cool) or Reverse (Heat)		

■ ERROR MESSAGE AND TROUBLESHOOTING

Symptom	Probable	Solution
<i>oPEr</i>	-Sensor break error -Sensor not connected	-Replace sensor -Check the sensor is connected correctly
<i>RdEr</i>	-A/D converter damage	-Unit must be repaired or replaced. -Check for outside source of damage such as transient voltage spikes.
<i>ReEr</i>	-Auto tune time out error	Set Pb, Ti, Td manually.
Keypad no function	-Keypads are locked -Keypads defective	-Set "Lo <u>BL</u> " to a proper value -Replace keypads
Process value unstable	-Improper setting of Pb, Ti, Td and CT	-Start AT process to set Pb, Ti, Td automatically -Set Pb, Ti, Td manually
No heat or output	-No heater power or fuse open -Output device defective or incorrect output used	-Check output wiring and fuse -Replace output device
All LED's and display not light	-No power to controller -SMPS failure	-Check power lines connection -Replace SMPS
Process Value changed abnormally	-Electromagnetic Interference (EMI) or Radio Frequency Interference (RFI)	-Suppress arcing contacts in system to eliminate high voltage spike sources. Separate sensor and controller wiring from "dirty" power lines. Ground heaters
Entered data lost	-Fail to enter data to EEPROM	-Replace EEPROM

FOR TECHNICAL ASSISTANCE

Please Call:

MORHEAT Inc.
170 Brockport Dr.,
Unit#97(South-
Side) , Toronto
Ontario, Canada
M9W 5C8
ph 416-675-7329
fx 416-675-7349

■ AUTOMATIC and MANUAL CONTROL

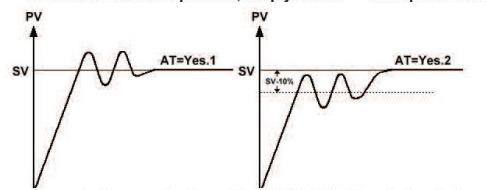
Automatic control is the normal mode of controller operation. In automatic control mode the controller automatically adjust the control output percentage by PID algorithm so that the PV=SV. The PID parameter Pb, Ti and Td can be also calculated by Auto Tune procedure.

Manual control allows the user to manually drive the output percentage from 0.0 to 100.0%. To access the manual mode, set the "*HRnd*" parameter to "YES", the rightmost decimal (MA) on SV display will flash. Then the "*ATL*" parameter will display alternately "*ATL*" and process value. The output percentage then can be adjusted by pressing UP or DOWN key.

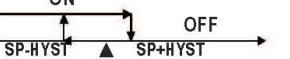
■ AUTO TUNE

In order to automatically set the PID parameter in PID level ("Pb" proportional band, "ti": integral time or reset and "td" derivative time or rate), first adjust the controller's set point to a value, which closely approximates your application. Set the "*RE*" parameter to "YES" for standard type auto tune or "YES2" for low PV type auto tune. The right-most decimal point (AT) on the PV display begins flashing. The auto tune procedure will take two cycle oscillations. After that, the controller performs PID control with the "learned" PID value to verify the results. Finally the PID values will be entered into the nonvolatile memory and then start the Fuzzy enhanced PID control. The auto tune process can last from several minutes up to two hours, depending on the system's parameter. A time out error will occur if the auto tune process can not be completed within two hours, in this case, try to set the PID parameters manually.

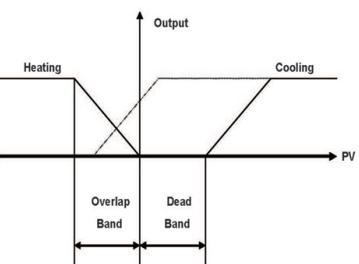
To abort an auto tune process, simply set the "*RE*" parameter to "no".



The controller can also be set to ON/OFF, PI, PD and P control mode. Set Pb = 0 for ON/OFF control mode. Set ti = 0 for PD control mode. Set td = 0 for PI control mode and ti, td = 0 for P control mode. The Hysteresis (dead band) of ON/OFF control can be set as follow:

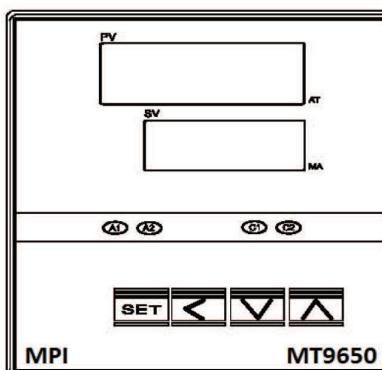


When the second control output (output 2) is equipped the proportional band of output 2 and dead band are defined as follow:



INSTRUCTION MANUAL FOR MT-50 SERIES FUZZY PID

■ FRONT PANEL DESCRIPTION :



(1)PV	—Process Value
(2)SV	—Setting Value
(3)AT	—Auto tuning LED
(4)MA	—Manual mode LED
(5)A1	—Alarm 1 LED
(6)A2	—Alarm 2 LED
(7)C1	—Control 1 LED
(8)C2	—Control 2 LED

(1) — SET KEY. Press once to access the next programmable parameter.

Press this key for 5 seconds to reset alarm timer.

(2) — UP KEY. Press to increase the set point or parameter value.

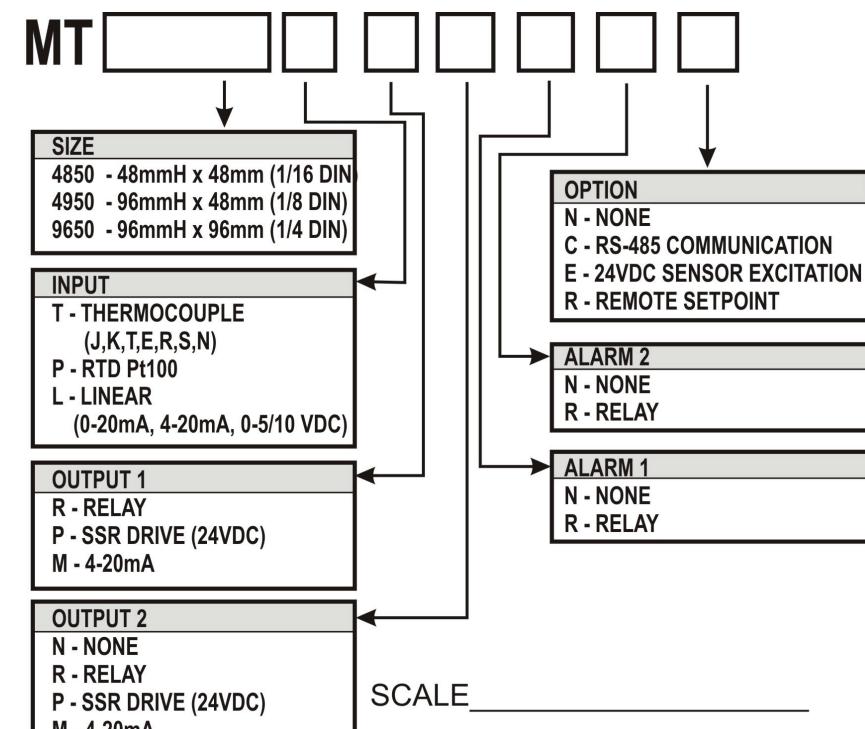
(3) — DOWN KEY. Press to decrease the set point or parameter value.

(4) — SHIFT KEY. Press the shift key for 5 seconds to execute Auto Tune process (Yes. 1 mode).

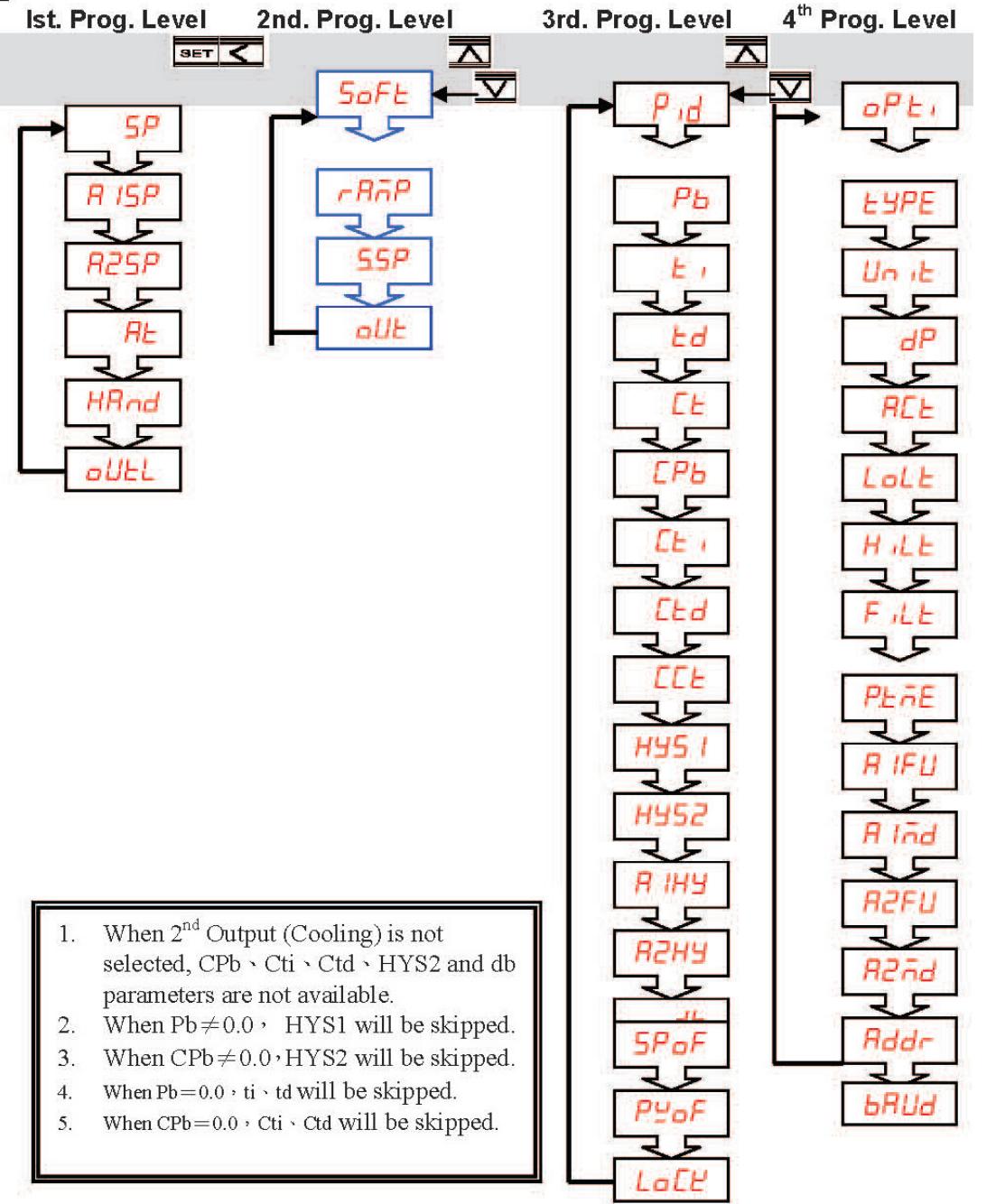
To abort the Yes. 1 Auto Tune process, press the shift key for 5 seconds.

(5) — Press the SET and UP keys once to return the normal operation.

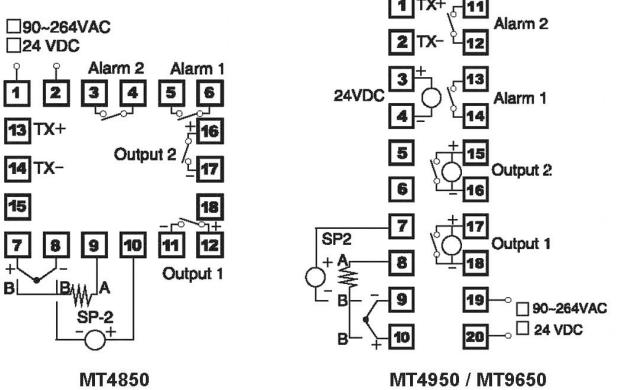
(6) — LEVEL KEY. Press the SET and SHIFT keys simultaneously for 5 seconds to select program level



PROGRAMMING LEVEL PARAMETERS



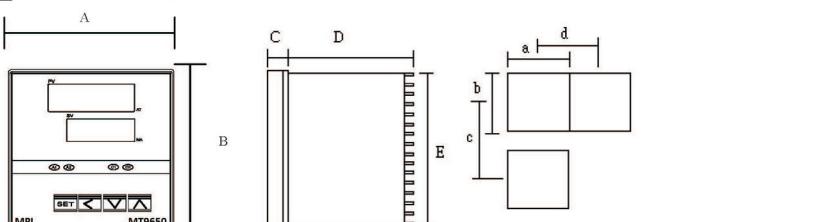
WIRING DIAGRAM



Wiring Precautions:

- Before wiring, verify the controller label for correct model number and option.
- For thermocouple input, use the appropriate compensation wire. And note the polarity of input signal.
- To avoid noise induction, keep input signal wire away from instrument power line, load lines and power lines of other electric equipment.

PANEL CUTOUT :



PARAMETER DESCRIPTION :

LEVEL Selection											
Press SET keys for at least 5 seconds to access Soft Level. Use ▼ or ▲ key to select programming level. Then press SET key to enter this level.											
<table border="1"> <thead> <tr> <th>LEVEL</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>Soft</td> <td>Soft Level</td> </tr> <tr> <td>Pid</td> <td>PID Level</td> </tr> <tr> <td>Opti</td> <td>Option Level</td> </tr> </tbody> </table>			LEVEL	Description	Soft	Soft Level	Pid	PID Level	Opti	Option Level	
LEVEL	Description										
Soft	Soft Level										
Pid	PID Level										
Opti	Option Level										

USER LEVEL

CODE	DESCRIPTION	RANGE	Default
SP	Set point value of control	LoLt — HiLt	500
R1SP	Alarm 1 set point value/Timer set value while A1FU is set to Ton or T. off, the unit can be HH.MM or MM.SS. It depends on the "P.tnE" parameter.	-1999 — 9999/00.00~99.99	10
R2SP	Alarm 2 set point value/ Timer set value while A2FU is set to Ton or T. off, the unit can be HH.MM or MM.SS. It depends on the "P.tnE" parameter.	-1999 — 9999/00.00~99.99	10
Re	Autotune no : Auto-tuning is disable YES! : Standard type auto-tuning. PV is compared with SV during auto tuning. YES2 : Low PV type auto-tuning. PV is compared with SV-10%FS during Auto-tuning.	no YES! YES2	no
HRnd	Manual control no : Disable the manual mode YES : Enable the manual mode.	no YES	no
OUTL	Output percentage. Adjustable when "Hand" is set to "Yes"	-100.0 — 100.0	0.0

SOFT LEVEL

Code	Description	Range	Default
rRnP	Ramp rate for the process value to limit an abrupt Change of process.(°C/min.)	0 - 9999 (0.0 - 999.9)	0.0
SSP	Set point value of soft-start	LoLt — HiLt	0
OUT	Output percentage of soft-start	0.0 - 100.0	100.0

PID LEVEL

CODE	DESCRIPTION	RANGE	Default
Pb	Proportional band variable. Set to 0.0 for ON/OFF control mode.	0.0-300.0%	10.0
ti	Integral time (Reset). This value is automatically calculated by activating the Auto tune function. If desired, the user can later adjust this parameter to better suit the application. When PB=0.0, this parameter will be not available. When set to zero, Pb & ti ≠ 0 for PI control.	0-3600sec	240

	calculated by activating the Autotune function. If desired, the user can later adjust this parameter to better suit the application. When PB=0.0, this parameter will be not available. When set to zero, Pb & td ≠ 0 for PD control.		
td	Derivative (Rate). This value is automatically calculated by activating the Auto tune function. If desired, the user can later adjust this parameter to better suit the application. When PB=0.0, this parameter will be not available. When set to zero, Pb & td ≠ 0 for PI control.	0-900sec	60
Ct	Proportional cycle time of output 1.	0-100sec	15
CPb	Proportional band variable for secondary control output (cooling). Set 0.0 for ON/OFF.	0.0-300.0%	10.0
cti	Integral time for secondary control output. When PB=0.0, this parameter will be not available. When set to zero, Pb & ct ≠ 0 for PI control.	0-3600sec	240
Ctd	Derivative time for secondary control output. When PB=0.0, this parameter will be not available. When set to zero, Pb & td ≠ 0 for PI control.	0-900sec	60
CCE	Proportional cycle time of output 2.	0-100sec	15
HYS1	Hysteresis for ON/OFF control on output 1.	0-2000(0.0-200.0)	1
HYS2	Hysteresis for ON/OFF control on output 2.	0-2000(0.0-200.0)	1
R1HY	Hysteresis of alarm 1.	0-2000	1
R2HY	Hysteresis of alarm 2.	0-2000	1
db	Dead band value. This defines the area in which output 1 and output 2 are both active (negative value) or the area in which output 1 and output 2 are both inactive (positive value).	-1000-1000 (-100.0-100.0)	0
SPoF	Set point offset. This value will be added to SV to perform control. It mainly used to eliminate offset error during P control.	-1000-1000 (-100.0-100.0)	0
PuoF	Process value offset. Permits the user to offset the PV indication from the actual PV.	-1000-2000 (-100.0-200.0)	0
LoCR	Parameter lock. This security feature locks out selected levels or single parameters prohibiting tampering and inadvertent programming changes.		
	0000 All parameters are locked out.		
	0001 Only SP is adjustable		
	0010 Only USER level is adjustable		
	0011 USER and PID levels are adjustable.		
	0100 USER,PID,OPTI levels are adjustable.		
	0101 USER,SOFT,PID,OPTI levels are adjustable.		

OPTION LEVEL

CODE	DESCRIPTION	RANGE	Default
IYPE	Input type selection.		
J	RANGE(°C) -50 ~ 1000	-58 ~ 1832	
K	-50 ~ 1370	-58 ~ 2498	
T	-270 ~ 400	-454 ~ 752	
E	-50 ~ 750	-58 ~ 1382	
B	0 ~ 1800	32 ~ 3272	
S	0 ~ 1750	32 ~ 3182	
N	-50 ~ 1300	-58 ~ 2372	
C	-50 ~ 1800	-58 ~ 3272	
D-Pt	-200 ~ 850	-328 ~ 1652	
J-Pt	-200 ~ 650	-328 ~ 1202	
LINE	-1999 ~ 9999		
Un it	Unit of process value °C : Degrees C. °F : Degrees F. Eng : Engineer unit for linear input.	°C °F Eng	°C °F Eng
dp	Decimal point selection. 0000 : No decimal point. 000.0 : 0.1 resolution 0.00 : 0.01 resolution, used for linear input only. 0.000 : 0.001 resolution, used for linear input only. After change decimal point, please reconfirm the parameter.	0000 000.0 0.00 0.000	0000 000.0 0.00 0.000
Re	Autotune no : Auto-tuning is disable YES! : Standard type auto-tuning. PV is compared with SV during auto tuning. YES2 : Low PV type auto-tuning. PV is compared with SV-10%FS during Auto-tuning.	no YES! YES2	no
RIFU	Output 1 control action. rEY: Reverse action for heating. dIR: Direct action for cooling.	rEY dIR	rEY dIR
LoLT	Low limit of span or range. Set the low limit lower than the lowest expected SV and PV display.	Full range	0
HiLT	High limit of span or range. Set the high limit higher than highest expected SV and PV display.	Full range	1000
FILE	Software filter. Time scale for timer alarm. HHmmHours:Minutes; nnss Minutes:Seconds	0.0-99.9	10.0
PEAE	Alarm 1 function. Refer to alarm function section for detail. If A1FU=None, it means alarm function is cancelled.	00.00-99.99	00.00
RI1D	Alarm 1 mode. Refer to alarm mode section for detail..	None, Hi, Lo, dif.H, dif.L, bd.Hi , bd.L, on, toFF	None
RI2D	Alarm 2 function. Refer to alarm function section for detail. If A2FU=None, it means alarm function is cancelled.	None, Hi, Lo, dif.H, bd.Hi , bd.L, on, toFF	None
Rend	Alarm 2 mode. Refer to alarm mode section for detail..	None, Stdy, Lath, StLa	None
Addr	Address of controller when communication with master device.	0 - 255	0
BRUD	Communication baud rate. 2.4k=2400bps, 4.8k=4800 bps, 9.6k=9600 bps, 19.2k=19200 bps	2.4k, 4.8k 9.6k, 19.2k	9.6k
ALARM FUNCTION			
A1FU/A2FU	ALARM TYPE	ALARM OUTPUT OPERATION	
none	Alarm function OFF	Output OFF	
H+	Process high alarm	ALSP → PV	
Lo	Process low alarm	ALSP → PV	
dFH	Deviation high alarm	SP+ALSP → PV	
dFL	Deviation low alarm	SP+ALSP → PV	
bdH+	Band high alarm	SP-ALSP → SP+ALSP → PV	
bdLo	Band low alarm	SP-ALSP → SP+ALSP → PV	
ton	On-timer	ALSP → SP → PV	
toFF	Off-timer	SP → OFF → PV	
ALARM MODE			
A1MD/A2MD	DESCRIPTION		
none	Normal alarm mode/ When timer function is selected, PV<SV timer function is not available.		
SEdY	Standby mode When selected, in any alarm function, prevents an alarm on power on. The alarm is enabled only when the process value reach alarm set point. Also known as "Startup inhibit" and is useful for avoiding alarm trips during startup.		
LATH	Latch mode. When selected, the alarm output and indicator latch as the alarm occurs. The alarm output and indicator will be energized even if the alarm condition has been cleared unless the power is shut off.		
5tLA	When Timer function is selected, PV< SV timer function is available.		
5tLH	Standby and latch mode		